### A Taste of Dynamic Information-Flow Control

15-136 Software Foundations of Security and Privacy

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## Motivation

...but it has its shortcomings.

- Incompatible with dynamic languages (Python, JS, ...)
- Annotation burden can be a showstopper for legacy code
- Every bit of the program must handle security explicitly

Secrecy level of data is determined at *run time*, rather than statically. Thought to be impossible until 2009, when Sabelfeld and Russo proved noninterference for such a language.

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Several advantages:

- More flexible and more permissive
- Easier for dynamic languages
- Simplifies migration of legacy code
- Security-aware code is more local

The Language

Same as before, but with a *classification* expression.

$$\begin{split} e &:= x \mid n \mid e_1 + e_2 \mid e_1 \times e_2 \mid e@l\\ p,q &:= \text{true} \mid \text{false} \mid p \land q \mid p \lor q \mid \neg p \mid e_1 = e_2 \mid e_1 \leq e_2\\ \alpha,\beta &:= x \leftarrow e \mid \alpha;\beta \mid \text{if } (p) \; \alpha \; \text{else} \; \beta \mid \text{while } (p) \; \alpha \end{split}$$

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(No typing rules are needed)

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Previous static checks generally become dynamic checks

Typing rule for static IFC:

$$\frac{\Gamma \vdash e_1: l_1 \qquad \Gamma \vdash e_2: l_2}{\Gamma \vdash e_1 \odot e_2: l_1 \sqcup l_2}$$

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Evaluation rule for dynamic IFC:

$$\frac{\langle \omega, e_1 \rangle \Downarrow_{\mathbb{Z}} n_1 @l_1 \qquad \langle \omega, e_2 \rangle \Downarrow_{\mathbb{Z}} n_2 @l_2}{\langle \omega, e_1 \odot e_2 \rangle \Downarrow_{\mathbb{Z}} (n_1 \odot n_2) @(l_1 \sqcup l_2)}$$

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**Evaluating Programs** 

 $\frac{}{\langle \omega, x \rangle \Downarrow_{\mathbb{Z}} \omega(x)} \qquad \frac{\langle \omega, n \rangle \Downarrow_{\mathbb{Z}} n@\bot}{\langle \omega, n \rangle \Downarrow_{\mathbb{Z}} n@\bot} \qquad \frac{\langle \omega, e \rangle \Downarrow_{\mathbb{Z}} n@l}{\langle \omega, e@l' \rangle \Downarrow_{\mathbb{Z}} n@(l \sqcup l')}$ 

(Boolean evaluation is similar)

 $\frac{\operatorname{Old}\operatorname{typing}\operatorname{rule}}{\Gamma\vdash e:l_e} \frac{l_e\sqcup\Gamma(pc)\sqsubseteq\Gamma(x)}{\Gamma\vdash x\leftarrow e}$ 

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$$\begin{split} & \text{New eval rule, success} \\ & \underline{\langle \omega, e \rangle \Downarrow_{\mathbb{Z}} n@l_n \quad \omega(x) = \_@l_x \quad l_{pc} \sqsubseteq l_x} \\ & \underline{\langle \omega, l_{pc}, x \leftarrow e \rangle \Downarrow \omega[x \mapsto n@(l_n \sqcup l_{pc})]} \end{split}$$

 $\label{eq:loss} \begin{array}{ll} \text{New eval rule, error} \\ \underline{\langle \omega, e \rangle \Downarrow_{\mathbb{Z}} n@l_n & \omega(x) = \_@l_x & l_{pc} \not\sqsubseteq l_x \\ \hline & \overline{\langle \omega, l_{pc}, x \leftarrow e \rangle \Downarrow \text{ error}} \end{array}$ 

 $\frac{\mathsf{Old typing rule}}{\Gamma \vdash e: l_e} \frac{l_e \sqcup \Gamma(pc) \sqsubseteq \Gamma(x)}{\Gamma \vdash x \leftarrow e}$ 

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 $\label{eq:linear_line$ 

• Uses so-called *no-sensitive-upgrade check*;  $l_n$  is not used.

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- Uses so-called *no-sensitive-upgrade check*;  $l_n$  is not used.
- NB The label of x can go up!

$$\frac{\langle \omega_1, l_{pc}, \alpha \rangle \Downarrow \omega_2 \quad \langle \omega_2, l_{pc}, \beta \rangle \Downarrow r}{\langle \omega_1, l_{pc}, \alpha; \beta \rangle \Downarrow r} \qquad \frac{\langle \omega_1, l_{pc}, \alpha \rangle \Downarrow \text{ error}}{\langle \omega_1, l_{pc}, \alpha; \beta \rangle \Downarrow r}$$

$$\frac{\langle \omega_1, l_{pc}, \alpha \rangle \Downarrow \omega_2 \quad \langle \omega_2, l_{pc}, \beta \rangle \Downarrow r}{\langle \omega_1, l_{pc}, \alpha; \beta \rangle \Downarrow r} \qquad \frac{\langle \omega_1, l_{pc}, \alpha \rangle \Downarrow \text{ error}}{\langle \omega_1, l_{pc}, \alpha; \beta \rangle \Downarrow \text{ error}}$$

Error stops execution

$$\label{eq:linear_states} \begin{split} \frac{\langle \omega, p \rangle \Downarrow_{\mathbb{B}} \mathsf{true} @l_p & \langle \omega, l_{pc} \sqcup l_p, \alpha \rangle \Downarrow r}{\langle \omega, l_{pc}, \mathsf{if} (p) \; \alpha \; \mathsf{else} \; \beta \rangle \Downarrow r} \\ \frac{\langle \omega, p \rangle \Downarrow_{\mathbb{B}} \mathsf{false} @l_p & \langle \omega, l_{pc} \sqcup l_p, \alpha \rangle \Downarrow r}{\langle \omega, l_{pc}, \mathsf{if} (p) \; \alpha \; \mathsf{else} \; \beta \rangle \Downarrow r} \end{split}$$

 $\begin{array}{ll} \underbrace{\langle \omega, p \rangle \Downarrow_{\mathbb{B}} \text{ true } @l_p & \langle \omega, l_{pc} \sqcup l_p, \alpha; \text{ while } (p) \; \alpha \rangle \Downarrow r \\ \\ \hline & \langle \omega, l_{pc}, \text{ while } (p) \; \alpha \rangle \Downarrow r \\ \\ \hline & \frac{\langle \omega, p \rangle \Downarrow_{\mathbb{B}} \text{ false } @l_p }{\langle \omega, l_{pc}, \text{ while } (p) \; \alpha \rangle \Downarrow \omega} \end{array}$ 

```
y <- true@L;
z <- true@L;
if (x) {y <- false@L};
if (y) {z <- false@L};</pre>
```

- y <- true@L; z <- true@L; if (x) {y <- false@L}; if (y) {z <- false@L};</pre>
  - What happens when x = true<sub>0</sub>H and when
    - x = false@H?

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y <- true@L;
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if (x) {y <- false@L};
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- What happens when x = true@H and when x = false@H?
- Can we write this program in the static language?

Noninterference

#### If a program $\alpha$

- runs on equivalent states  $\omega_1 \approx_l \omega_2$ , and
- both runs successfully terminate:  $\langle \omega_1, l_{pc}, \alpha \rangle \Downarrow \omega'_1$  and  $\langle \omega_2, l_{pc}, \alpha \rangle \Downarrow \omega'_2$

then the final states are equivalent  $\omega_1' \approx_l \omega_2'$ .

$$\frac{l_n \sqsubseteq l}{n@l_n \approx_l n@l_n} \qquad \frac{l_1 \not\sqsubseteq l \qquad l_2 \not\sqsubseteq l}{n_1@l_1 \approx_l n_2@l_2} \qquad \frac{\forall x. \ \omega_1(x) \approx_l \omega_2(x)}{\omega_1 \approx_l \omega_2}$$

- Expression evaluation respects equivalence: if  $\omega_1 \approx_l \omega_2$ and  $\langle \omega_i, e \rangle \Downarrow_{\mathbb{Z}, \mathbb{B}} r_i$ , then  $r_1 \approx_l r_2$ .
- Confinement: if  $\langle \omega, l_{pc}, \alpha \rangle \Downarrow \omega'$  and  $l_{pc} \not\sqsubseteq l$ , then  $\omega' \approx_l \omega$ .
- $\cdot \approx_l$  is an equivalence relation.

Use induction on the execution length.

Wrapping up

- Static IFC languages: Jif (based on Java), FlowCaml (based on OCaml), SPARK (based on Ada), ...
- Research IFC OSs: HiStar, Asbestos, ...
- Taint tracking in Perl, Ruby, etc
- Dynamic IFC languages and libraries: JavaScript monitors, LIO (Haskell)

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# Demo!

#### Some references:

- "From Dynamic to Static and Back: Riding the Roller Coaster of Information-Flow Control Research." Sabelfeld and Russo, 2009. (First dynamic IFC language with a proof of noninterference.)
- "Flexible Dynamic Information Flow Control in Haskell." Stefan et al., 2011.